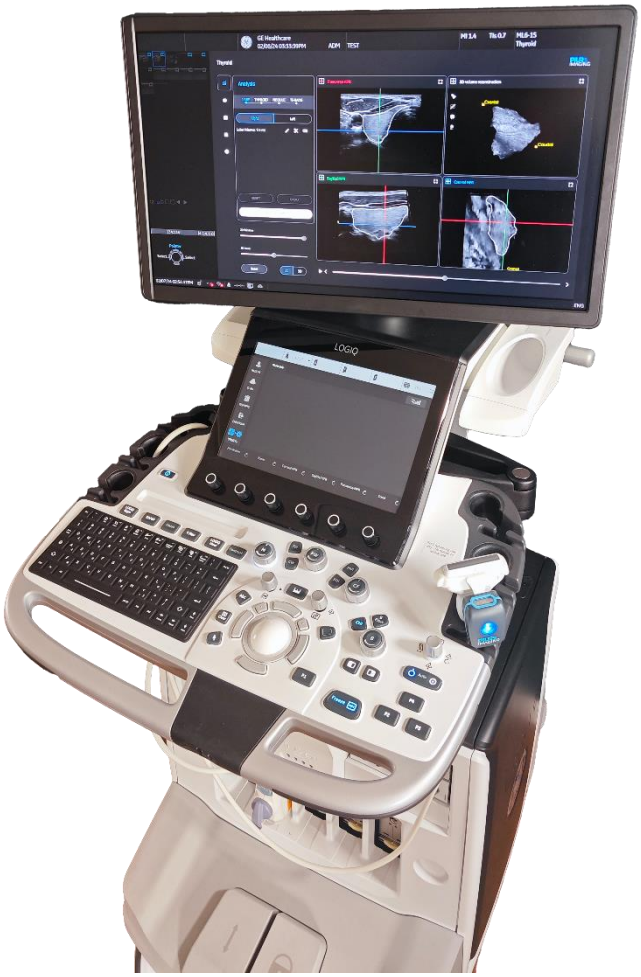
# *PIUR® tUS inside*

## User Manual



# User Manual

## *PIUR® tUS inside*

Document Revision 9.0

Software version: 1.0

Type: PIUR tUS inside







Hamburgerstrasse 11 / TOP7

1050 Vienna

Austria

# Table of Contents

# 1 General Information

## 1.1 Abbreviations and Terms

| Abbreviation / term | Description |
|---|---|
| US | Ultrasound |
| tUS | Tomographic ultrasound |

## 1.2 Symbols in User Manual

| Symbol | Description |
|---|---|
|  | Helpful **information**, which simplifies daily work with the device. |
|  | **Attention:** Important information that should be understood prior to operating the device. |
|  | **Safety notice.** Situations in which misuse can lead to personal injury or damage to property. |

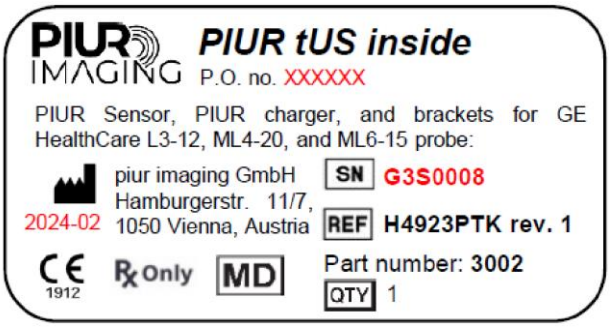
## 1.3 Symbols on the device

| Symbol | Description |
|---|---|
|  | Stand-by symbol |
|  | Charging |

### 1.3.1 Identification Labels

**PIUR tUS inside – System Label**

The system Label is affixed on Shipping box.

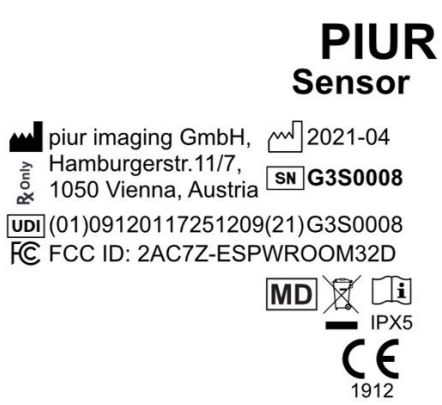


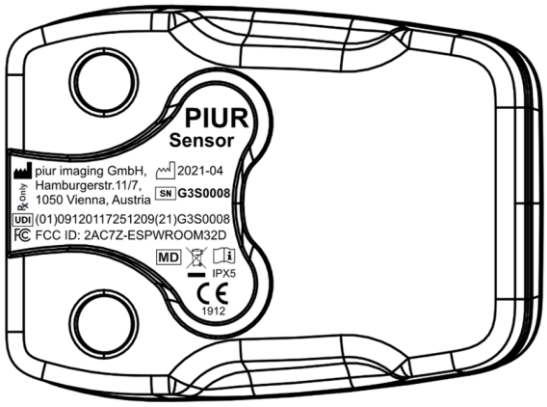

**PIUR tUS inside Software**

The identification label is displayed in the software itself (software user interface), in plain-text format.

The label with the corresponding software version and UDI parameters (UDI-DI+UDI-PI), can be used to identify the device. Please note down the software version before contacting the PIUR service.

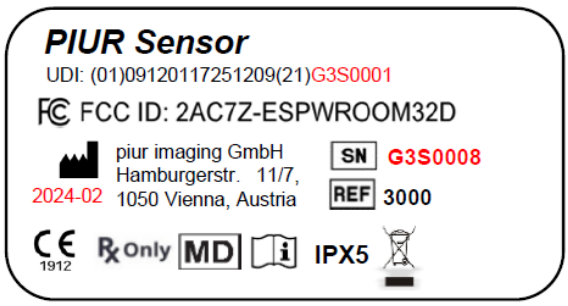
**PIUR Sensor**

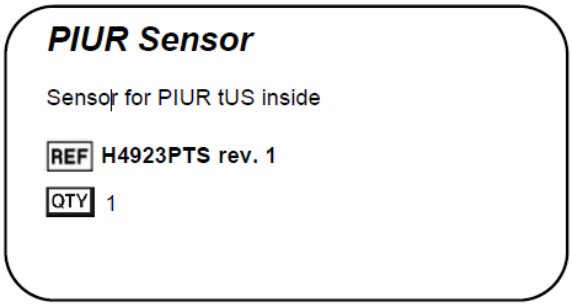



**PIUR Sensor Box**

Sensor packaging Label is affixed on the PIUR Sensor Box.

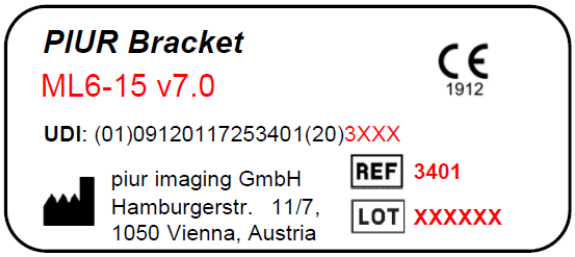


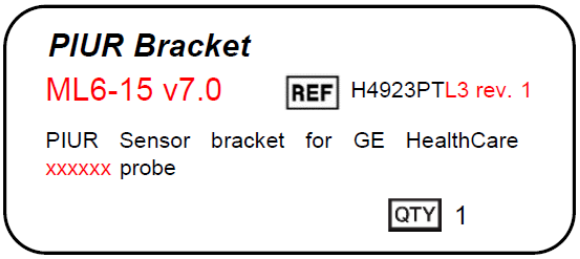




**PIUR Bracket**

Label specification for PIUR Bracket contains Model type, Version number and REF number (depending and based on the type).

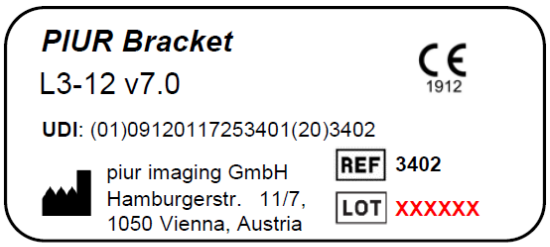
The Label is affixed on the PIUR Bracket packaging box.

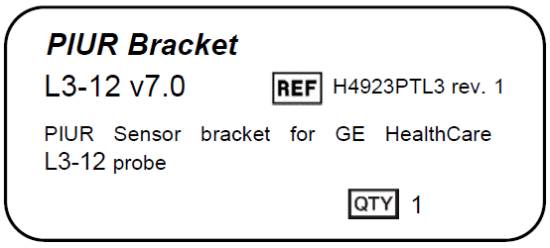


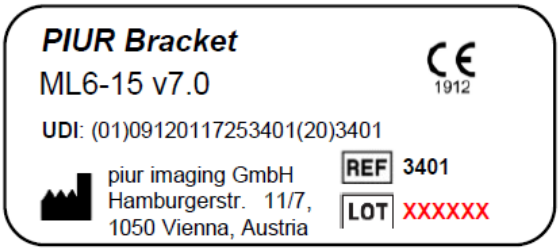
**Variants for the three probes:**

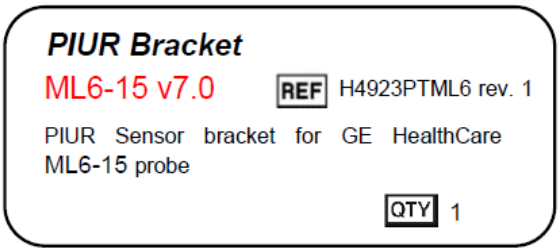
**L3-12 Probe**



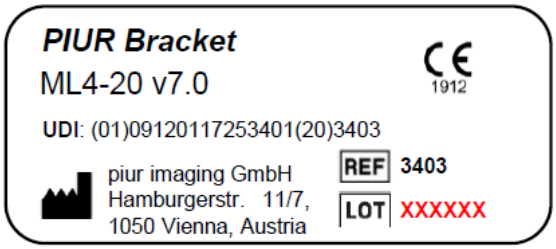



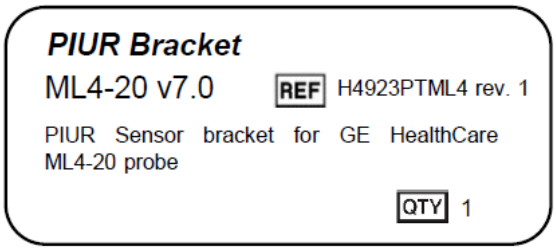

**ML6-15 Probe**



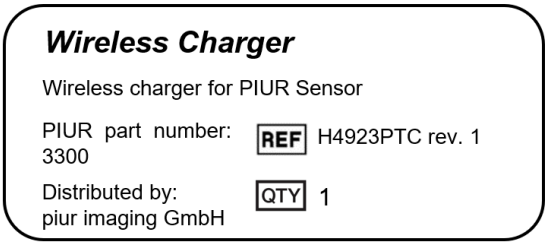

**L3-12 Probe**



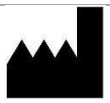




**Wireless Charger**

The Label is affixed on the PIUR tUS inside shipping box.



The following additional symbols can be found on the identification label:

| Symbol | Description |
|---|---|
| UDI | UDI Carrier label, containing UDI-DI + UDI-PI parameters, displayed in HRI (human readable interpration). |
|  | Manufacturer |
| CE 1912 | CE mark with Notified Body number (ID) |
|  | Operating instructions |

## 1.4 Function of this Document

This document provides a detailed description of the PIUR tUS inside system and its use within the scope of the application domain it was designed for. It provides instructions for use (IFU) to help the user in the safe and correct operation of the system.

## 1.5 Intended Use

The PIUR tUS inside serves as a non-invasive, transient and active medical device that is intended to support the user with the examination of thyroid and thyroid nodules, by providing 3D information. 2D ultrasound images, acquired by a compatible GE Healthcare ultrasound device and position data, generated by the system-integrated PIUR Sensor, are the basis for 3D image reconstruction. The PIUR tUS inside consists of software and hardware components, including the PIUR Sensor and PIUR Bracket.

The PIUR tUS inside software is integrated in the GE Healthcare ultrasound device environment (device), which must be a medical device according to MDR 2017/745 with a valid CE-Label. The compatible GE Healthcare can be found under section 4.3.1, supported ultrasound devices.

The PIUR tUS inside acts as part of the diagnostic chain only and must not be used as a sole source for treatment decisions.

PIUR tUS inside device is not intended for body contact and surgery (including skin, mucosal membrane, breached or compromised surfaces, blood path indirect, tissues, bones, dentin, or circulation blood). RM-34 RM-140 RM-141

## 1.6 Disclaimer

The manufacturer is not responsible for improper use, failure to comply with the safety notes and non-observation of specifications due to negligence. piur imaging only assumes responsibility for the safety and reliability of the PIUR tUS inside system and accessories when all changes, enhancements, repairs and other work to the application have been performed by an authorized dealer of piur imaging and certified service person, or piur imaging directly and the User Manual has been observed before and during device operation.

**Safety Notice**: Do not modify this software application without authorization of the manufacturer.

## 1.7 General Residual Risk including significant Risks

Considering possible sources of failure, foreseeable and unforeseeable errors of use and after risk mitigation residual risk of this medical product remain. Within the Risk Management process, a total of 90 residual risks have been identified. There following residual risks are considered as significant:

- Wrong image information

As a diagnostic system the most relevant output of the device is image information. This image information can influence medical decision in terms of therapy, treatment, prevention or further alternative diagnostic information. Caused by various factors the system may display incorrect image information after the image reconstruction. This wrong image information can be caused by erroneous input of image or tracking source or by software or user errors. The wrong image information can either appear as bad image quality or unrealistic image content in terms of anatomical appearance. In both cases the error is obvious to the user. In rare cases the wrong image information can display anatomically reasonable content that cannot be identified as obvious wrong image information and therefore may mislead the user and lead to undesired consequences- in the worst case not getting necessary interventions or surgery or getting unnecessary intervention and surgery. This residual risk affects the patient.

- Incorrect measurement

Measurement features as part of the software can influence the diagnostic decision and therefore effect further therapy, treatment, prevention or further alternative diagnostic information of the patient. Due to various sequences of internal or external event, errors of use or inadequate image input measurement errors can occur. Especially out of plane (length) measurements depend on appropriate use and adequate image input with sufficient frame rate. The residual risk is a measurement deviation outside of the disclosed error range that may lead to wrong image information as the residual risk above “Wrong image information”. The This residual risk affects the patient. For further details of measurement deviation and errors please see chapter 9.2 Measurement Function.

- Infection

Infection is a risk that can occur with any device that comes into contact with the human body, including sensors and attachments. However, it can be easily prevented with proper cleaning techniques. To reduce the risk of infection, it is important to regularly clean and disinfect the sensor and its attachments as recommended in the user manual (chapter 7.3). Failure to do so can lead to the accumulation of bacteria and other harmful microorganisms, which can cause infection and other health problems. By following the correct cleaning procedures, you can help ensure the safety and effectiveness of your device and protect yourself and others from potential health risks.

All residual risks are accepted and considered under the scope of the Risk Management file.

## 1.8 Recommendations regarding cybersecurity:

The PIUR tUS inside system is embedded in an existing Ultrasound device and therefore follows the cybersecurity recommendations from the ultrasound manufacturer. RM-13

The installation process is provided by the US manufacturers (here GE Healthcare) e-delivery system and follows the cybersecurity recommendations from the ultrasound manufacturer.

Backup and restoring is controlled by the US environment and follows the cybersecurity recommendations from the ultrasound manufacturer.

Detection and reporting of cybersecurity vulnerability or incident is communicated to the responsible US manufacturer. RM-16

## 1.9 Contact and Regulatory Information

PIUR tUS inside is classified as non-invasive, transient and active medical device of Class IIa, in accordance with the Medical Device Regulation (EU) 2017/745, Annex VIII.

The conformity of this product according to the general safety and performance requirements of MDR (EU) 2017/745 was proved with the Conformity Assessment Procedure according to Annex IX.

The manufacturer documents that with the CE-Label.

**piur imaging GmbH**

Hamburgerstr. 11 / Top 7

1050 Vienna

Austria

CE

# 2 Safety Regulations

The assembly of medical electrical systems and changes during the actual service life require a check with regard to the requirements set out in EN 60601-1 clause 16. Electrical installations in the room where PIUR tUS inside is used shall comply with the following:

Do not modify this equipment without authorization of the manufacturer.

EN 60601-1 Kap. 7.9.3.1

The system is suitable for use in hospitals and professional healthcare environment except for near active HF surgical equipment and the RF shielded room for magnetic resonance imaging, where the intensity of EM disturbances is high.
EN 60601-1-2 Kap. 5.2.1.1. a)

Use of this equipment adjacent to or stacked with other equipment should be avoided because it could result in improper operation. If such use is necessary, this equipment and the other equipment should be observed to verify that they are operating normally.

EN 60601-1-2 Kap. 5.2.1.1. c)

Use of accessories and cables other than those specified or provided by the manufacturer of this equipment could result in increased electromagnetic emissions or decreased electromagnetic immunity of this equipment and result in improper operation.
EN 60601-1-2 Kap. 5.2.1.1. e)

Portable RF communications equipment (including peripherals such as antenna cables and external antennas) should be used no closer than 30 cm (12 inches) to any part of the PIUR Sensor, including cables specified by the manufacturer. Otherwise, degradation of the performance of this equipment could result.
EN 60601-1-2 Kap. 5.2.1.1. f)

If malfunctions and defects occur.

**Occurrence of malfunctions and defects can lead to personal injury or damage to the device.**

If malfunctions and defects occur, discontinue the use of the PIUR tUS inside system and inform our service team via the above contact details (also chapter 6).

The Sensor contains LED for skin illumination. During the acquisition, this LED should not face the eye. RM-175

Do not exchange batteries without authorization of the manufacturer

## 2.1 User Requirements for Use

- The user has been officially trained by an authorized person in using PIUR tUS inside and is issued with a corresponding certificate.
- The training is provided by authorised service personal and follows the training protocol.
- The training includes system setup, image review, application use, typical errors of use, possible system errors and app closing.
- The system includes turning the sensor on and off, charging, cleaning and an introduction to the LED signals.
- The assistants have carefully read and understood the User Manual.
- The user is required to observe the safety instructions and to adhere to the safety provisions.
- The user has to be a physician skilled in ultrasonic diagnosis.
- Users have knowledge of human anatomy.
- Users have practical experience in the use of ultrasound for medical diagnostics and the fields of applications in which they use PIUR tUS inside.
- Patient should not move during the image acquisition as it could possibly lead to a wrong image data. RM-154
- The acquisition should be performed with the recommended speed of 0.5- 2 cm/s. RM-101

# 3 Product Information

## 3.1 Functionality of the PIUR tUS inside

*PIUR tUS inside* (Figure 3) is a medical device, which enhances standard ultrasound devices with a three-dimensional tomographic imaging method for a 3D analysis of ultrasound volumes. With PIUR tUS inside,examining physicians can make diagnostic decisions based on standard 2D as well as 3D image data integrated in an ultrasound device environment. This 3D data provides information which previously could have only been generated using other 3D imaging technologies like CT or MRI.

*Figure 1: PIUR tUS inside*

Three-dimensional ultrasound is already a common method in certain clinical areas. Ultrasound device manufacturers offer methods to create 3D image data. However, the technologies used for 3D image creation vary considerably and all of them have limitations for the imaging of anatomical structures. In order to visualize complete thyroid structures, the system needs to be able to perform non-linear scans measuring up to 20cm.

The PIUR tUS inside runs on a compatible GE Healthcare ultrasound system. It takes as an input a sequence of 2D ultrasound images that are transmitted through a software interface from the ultrasound to the PIUR tUS inside. In addition, the PIUR Sensor must be clipped onto the ultrasound transducer using individually designed attachments. For image acquisition, the user moves the 2D ultrasound transducer perpendicular to the structure to be imaged over the region of interest of the patient's body. An inertial measurement unit (IMU), which is built into the PIUR Sensor, tracks the orientation of the transducer during the scan and sends this information to the ultrasound via Bluetooth (Figure 4). The PIUR tUS inside combines image information and sensor information to generate tomographic 3D ultrasound volumes on which image analysis can be performed.

One important property of this method is the unlimited length of the acquired volume. PIUR tUS inside therefore allows recording and analyzing a complete thyroid lobe.


*Figure 2: Acquisition principle*

## 3.2 Clinical Indications

The PIUR tUS inside is used to examine thyroid and thyroid nodule.

## 3.3 Contraindications

- On patients with open wounds or irritated skin
- During surgery

## 3.4 Clinical benefits

Key Features and benefits of the PIUR tUS inside Thyroid application:

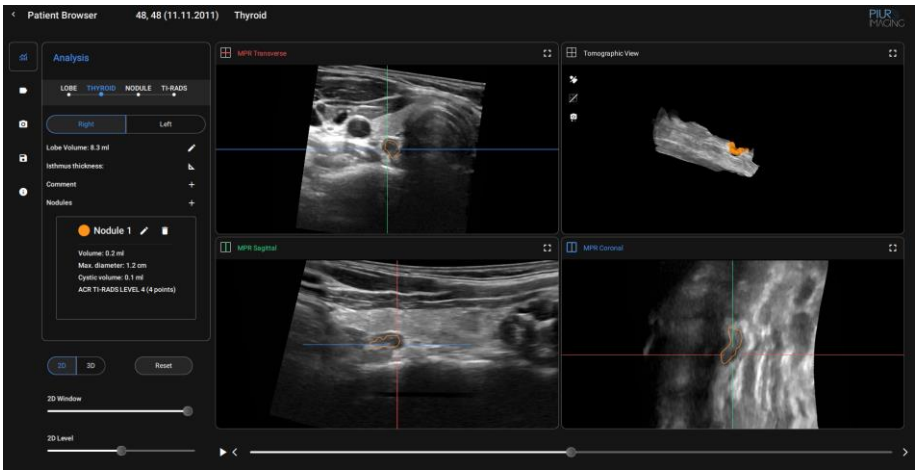
- Multi-planar reconstructions
- Voxel-based volume measurements
- Semi-automatic* lobe segmentation and volume measurements
- Semi-automatic* nodule segmentation, volume measurements, and ACR TI-RADS classification
- Standardized reporting
- 3D Visualization of lobe and nodules
- Visual explanation of disease and treatment decisions to patient
- Full image documentation of lobe and nodules in one volume scan
- Side-by-side comparison of two datasets to monitor disease progression over time
- Reduced inter- and intra-observer variability compared to standard 2D ultrasound
- Possibility of retrospective analysis of acquired image data

* The systems automated suggestions have to be accepted by a trained user, thus semi-automatic.

# 4 System components and Initial Use

## 4.1 Delivery Package

The deliver package consists of the e-delivered PIUR tUS inside software application installed or installable on the compatible GE Healthcare ultrasound device.




PIUR tUS inside Software

## 4.2 Components and Accessories (separate)

PIUR tUS inside requires the following components for acquiring tracked scans for 3D reconstruction.

PIUR Bracket
(depending on ultrasound transducer)
REF 34XX

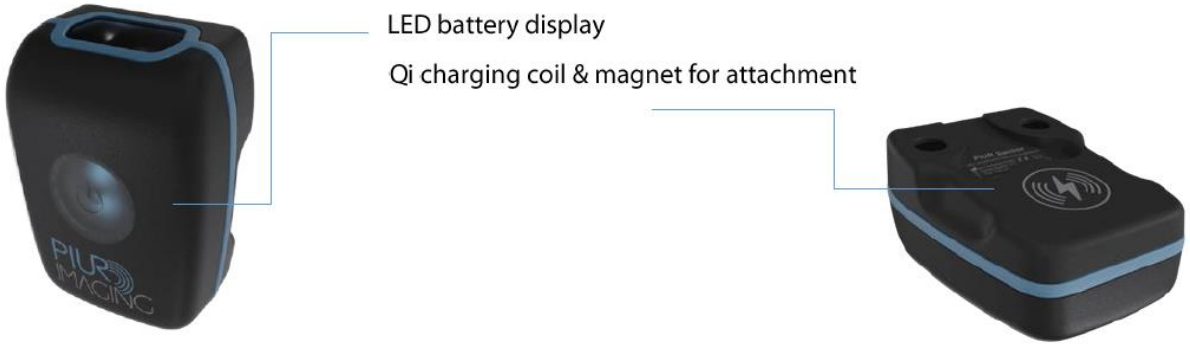
PIUR Sensor
REF 3000

Wireless charger
REF 3300


PIUR Sensor Quick Guide

## 4.3 Equipment of the main components

**Properties**




The PIUR Sensor provides information about movement of an ultrasound transducer. it is embedded in a protective housing, which is fixed to the ultrasound transducer through an attachment. The PIUR Sensor can be charged using the provided wireless charger through the Qi 1.2 standard. The Sensor connects to other devices through a Bluetooth interface.

**Information:**

LED display provides information about the system status.

**The PIUR Sensor falls into sleep-mode if battery status is lower than 10% or if sensor has been disconnected for 10 minutes.**

Sensor can be re-started manually by pressing the start-button

The PIUR Sensor should be charged immediately after it shows battery status low and before it is not in use for a longer period. EN 60601-1 Kap. 7.9.2.4

Do not connect other Bluetooth devices as headsets or phones with the computer while using the PIUR Sensor RM-111

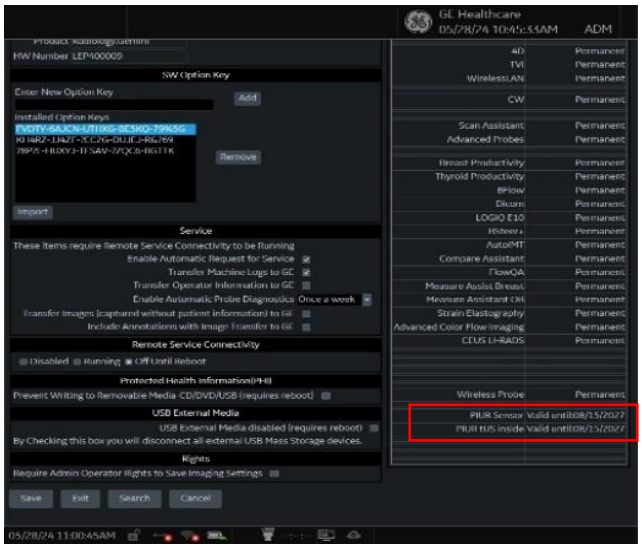
The damage of the sensor window from sharp tools or strong mechanical forces can result in harm to the internal electronics, consequently, lead to the non-usable system

| Status | Colour | Position |
|---|---|---|
| Sensor is charging | blinking green | On the charging Dock |
| Sensor fully charged =100% | static green | On the charging Dock |
| Sensor after turned on & searching for connection (Sensor <15%) | blinking orange | During use |
| Sensor after successful connection (Sensor <15%) | fast blinking orange | During use |
| Sensor after turned on & searching for connection (Sensor >=15%) | blinking blue | During use |
| Sensor after successful connection (Sensor >=15%) | static blue | During use |
| Sensor lost connection | blinking blue | During use |
| Sensor has error | fast blinking yellow | During use |
| Sensor startup | static white | During use |

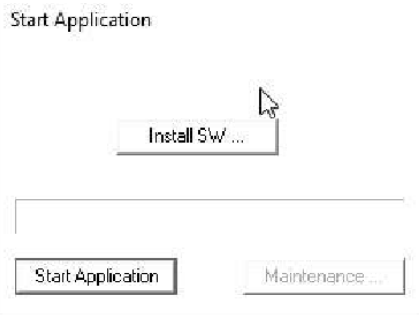
## 4.4 Installation Process

1. Check if there is an available option key for “PIUR tUS inside” on the option key sheet.
2. Enter the option key in the Utility+ -> Admin section.

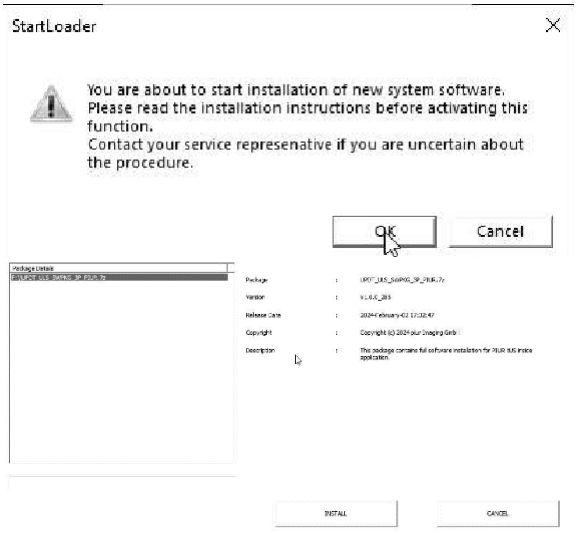
3. Verify after restart, if the product keys were accepted by verifying the option keys “PIUR Sensor” and “PIUR tUS inside” appearing in the option key status list




4. Plug-in the USB which contains the software installation files to an available port on the machine.
5. Start the GE ultrasound machine.
6. Execute the installation setup file of software by performing following steps:

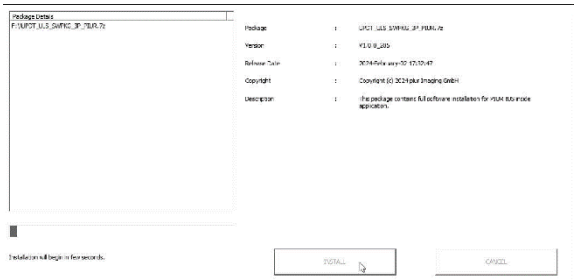



In the "Start Application" window, locate and click on the "Install SW" button to initiate the software installation process.




A dialog box labeled "StartLoader" will pop up. Click on "OK" to proceed.

Select the installation package by navigating to "F:\UPDT_ULS_SWPKG_3P_PIUR.7z"
Once the correct package is selected, click on the "Install" button to begin the installation process.



After clicking "Install", the GE System installation interface will appear, and the installation process will commence shortly.

GE System installation should appear and installation begins


During installation, a logo of Ultrasound model will display at the center of the screen.
Wait until the installation is finished
Once the installation process is finished, you are ready to start working with the software.

## 4.5 Switching the PIUR Sensor on and off and connect to GE Healthcare US device

1. Turn on the sensor by pressing the Power Button


2. A blinking blue LED light will signal that the sensor is operational
3. If not in use for several minutes, the sensor will automatically turn off
4. It can be turned off manually by pressing the Power Button, the GE Healthcare device will display a blue and red bar (see the Acquisition Workflow), that the sensor is disconnected
5. Select "SCAN" on the GE device touch panel and swipe on the screen to the left
6. Select "PIUR Sensor" as position sensor type
7. A static blue LED light on the sensor as well as a green signal bar on the GE Healthcare device will (see the Acquisition Workflow) signal that the sensor is connected to the GE Healthcare US device.

Make sure the PIUR Sensor is fully charged before operations.

## 4.6 Securing the Sensor Attachment to the Probe

### Sensor (PIUR) Bracket


1. Turn the probe as shown in the picture

2. Hook the PIUR Bracket to the right side of the probe and pull the clip on the Bracket plate over the sensor head until it locks into place with a click. Ensure the correct orientation of the probe.

3. The attachment must be correctly locked in and secured

**Information:** Follow the User Manual in the reverse order to disassemble the clip.

**Safety Notice:** Use of not certified Attachments

- Only officially Brackets delivered by piur imaging GmbH are allowed to use with the device.

## Securing the Sensor Housing on the front Bracket

1. Place the sensors on the Bracket docking plate. The sensor should be attracted easily by the docking plate.


2. Make sure the sensor is snapped in properly before continuing with the acquisition workflow.

**Information:** Follow the User Manual in the reverse order to disassemble the attachment.

# 5 Acquisition Workflow

After completing sections 4.4, 4.5, and 4.6, execute the following steps:

1. Ensure proper connection of the PIUR Sensor to the GE device. The connection will be indicated by:
   a. Green bar on the GE device screen
   b. Constant blue light on the PIUR sensor (described in chapter 4.3 and 7.7)
2. Position the probe, including the PIUR Sensor, on the patient's neck and locate a caudal/cranial position below/above the thyroid gland.
3. After positioning the probe, start the acquisition by pressing the "Mark Cine" button on the GE device.
4. Begin scanning by moving the probe from caudal to cranial / cranial to caudal along the entire side of thyroid. Continue the motion until the probe is positioned cranial above / caudal below the thyroid.
5. Press the "P1" button on the GE device to end the acquisition (see in Tips/Information for the acquisition, Button “P1”).
6. If you want to stop the ongoing scan, press the "Mark Cine" button again. This action will cancel the current acquisition (see in Tips/Information for the acquisition, Button “Mark Cine”).
7. Confirm the tracked loop with the blue cine icon appearing on the cine loop on the left panel (see in Tips/Information for the acquisition, Tracked and untracked loop).
8. Redo process for unscanned thyroid side.
9. After the acquisition was performed, make sure the cine loop marker next to the scan thumbnail on the left side appears in blue, confirming that the scan contains tracking information. If this appears grey, see the following tips/information.

**Tips/information for the acquisition:**

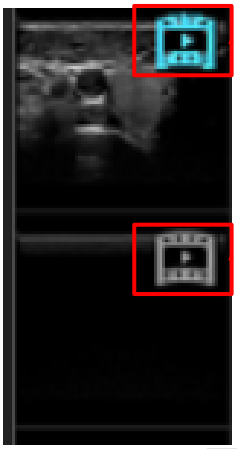
- Move the probe with constant speed, do not stop during sweep for diagnosis
- Make sure the whole thyroid gland is visible during the acquisition time of the probe movement. Change to a larger probe or turn on virtual convex if whole gland is not visible
- Make sure the acquisition includes the whole caudal and cranial end of the thyroid gland
- Be aware that dropping of the scan can occur by clicking the cine mark again, posing a risk of unintentionally discarding the scan.
- Be aware that only the scans with the blue cine loop marker contain the sensor tracking information. If the marker is grey, the sensor information is missing
- Sensor connection is confirmed by the green bar on the screen and the constant blue light on the sensor
- Sensor disconnection can happen due to:
- Entering sleep mode of the sensor (triggered 10 min after not using)
- Sensor battery level is too low

- Sensor is not selected on the GE device as tracking device
- Button Icons Table


Button “P1”



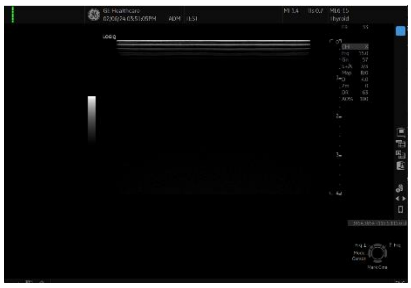
Button “Mark Cine”

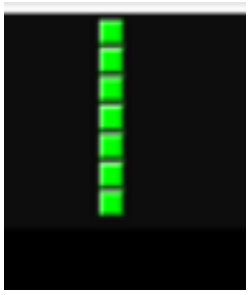


Tracked Loop

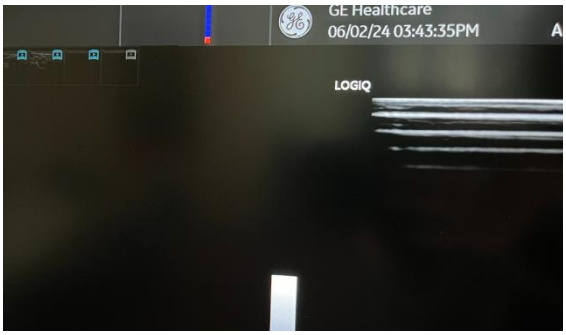
Untracked Loop

Tracked and untracked loop





Green Bar




Blue and Red bar (the sensor is disconnected)

# 6 Review Workflow

## 6.1 Switching on PIUR tUS inside software

The software application is started by the user interface on the GE Healthcare US device.
From the GE Healthcare US device user interface move to “Utility+” menu. From there you can select the PIUR inside application via touch screen

## 6.2 User interface overview

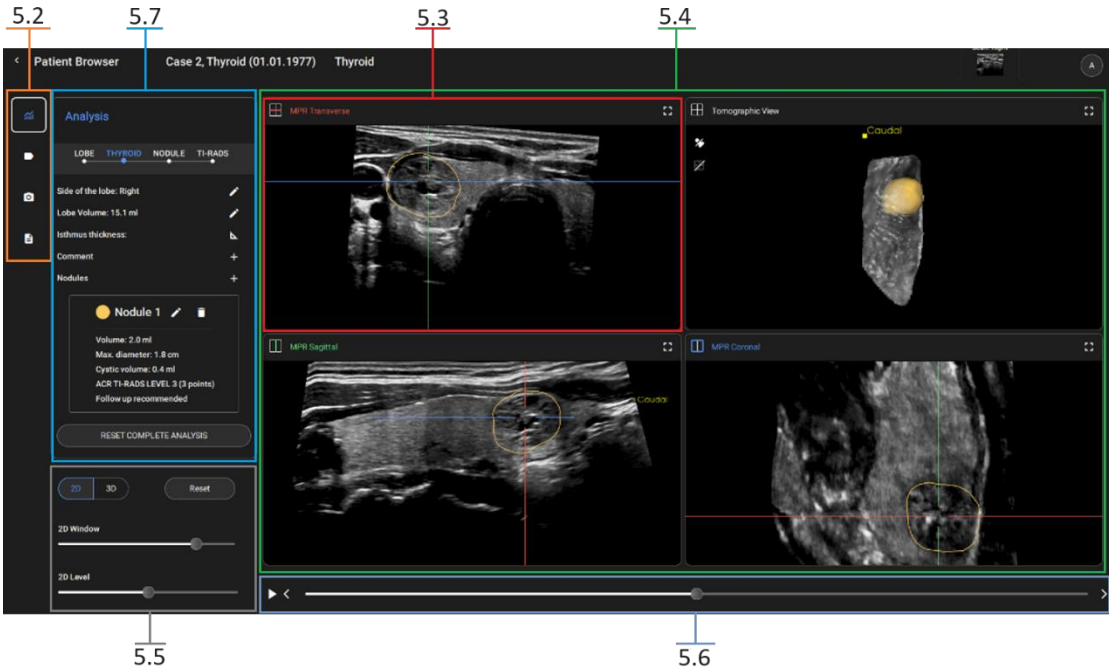



*Figure 3: Software main screen overview*

**5.2** Tool selection
**5.3** MPR Transverse
**5.4** 2D/3D views: MPR Transverse, Tomographic View, MPR Sagittal, MPR Coronal
**5.5** Window/Level settings
**5.6** MPR Slider
**5.7** Thyroid Analysis Workflow

## 6.3 Tool Selection

| | |
|---|---|
|  | Analyse Lobe and Nodules, see chapter 6.9 |
|  | Annotations + Measurements, see chapter 6.10 |
|  | Creates a Screenshot of the entire screen and stores it on the GE Healthcare US device. |
|  | Saves all measurements and transfers them to the device database. Warning: Once you saved the analysis, you cannot update or revert this action! |
|  | View Information and Label |

## 6.4 3D view

The 3D view is controlled by:

| Icon | Function | Description |
|---|---|---|
|  | Zoom | Move the cursor to the 3D view. Right click and hold the click. The cursor indicates the current function. Move the trackball down to zoom out, move the trackball up to zoom in. |
|  | Rotate | Move the cursor to the 3D view. Left click and hold the click. The cursor indicates the current function. Move the trackball to rotate the 3D model. |
|  | Move | The Move function is triggered by switching the mode. The mode switches between move and rotate function.<br>After switching the mode, left click and hold the click. The cursor indicates the current function. Move the trackball to move the 3D model. |

The 3D View tools:

| Icon | Function |
|---|---|
|  | Enables the Visualization of the used transducer for the scan. The transducer follows the actual scan movement. |
|  | Disables the Visualization of the used transducer. |
|  | Disables the MPR planes (Transversal / Sagittal / Coronal) to be shown in the 3D view |
|  | Disables the MPR planes (Transversal / Sagittal / Coronal) to be shown in the 3D view. |
|  | Toggles Visualization. Mode according to default grey Ultrasound image and orange colored Ultrasound image |
|  | Navigating through the image layers in 2D and rotating the volume in 3D is activated. |
|  | Moving the images is activated. |

## 6.5 MPR view

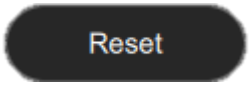
MPR (2D) control units:

| Icon | Function | Description |
|---|---|---|
|  | Scroll | Left Click in in the picture in any MPR view. Hold the mouse click. The cursor indicates the function. |
|  | Zoom | Right Click in the picture in any MPR view. Hold the mouse click. The cursor indicates the function. |
|  | Move | The Move function is selected by default. Left click into one MPR view and hold to move the dataset. |
|  | Rotate | Move the cursor on the MPR lines, but away from the center of the cross. The cursor indicates the function switching from move to rotate. Click and hold the Left Mouse pointer to rotate the selected MPR line.<br>After releasing the click, the dataset will stay in the rotated state. Use the reset function to get back to the original view. |

## 6.6 Window / Level settings


The brightness and contrast can be changed by the slider.


Choose between 2D and 3D, to apply on the 2D MPR or 3D view.




Reset the orientation of the MPR and 3D to default.Reset the brightness of the image for 2D and 3D.

## 6.7 MPR slider

The slider moves along the orientation of the Transversal MPR plane. The bar can be moved with the slider. Or a playback can be started/paused with the button. The left and right arrows can be also used for moving individual slices.

## 6.8 US device controls

The US device provides embedded user interaction keys to interact with the application.

Controls the scroll bar (refer to 6.7)

Moves transversal plane

Moves sagittal plane

Moves coronal plane

No symbol, labeled "Zoom" on touchpad

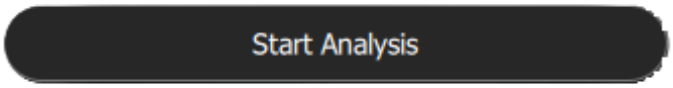
Controls Zoom


Controls window (2D/3D)

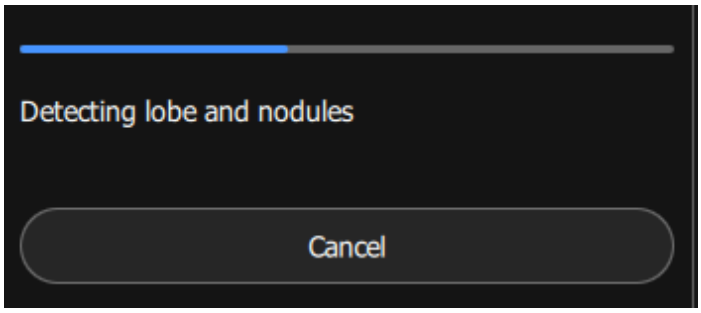

Controls level (2D/3D)

## 6.9 Thyroid Analysis workflow


Menu Wizard



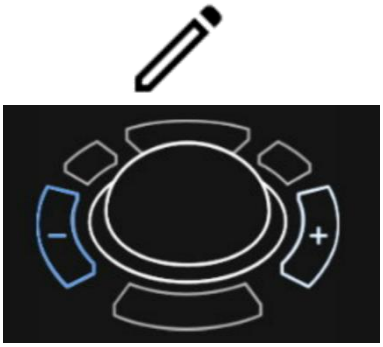

Press "Start Analysis" to trigger the prediction of the AI Network.




The progress bar gives indication regarding the process. There is also the option to cancel. Pressing cancel stops the analysis and the "Start Analysis" button appears.

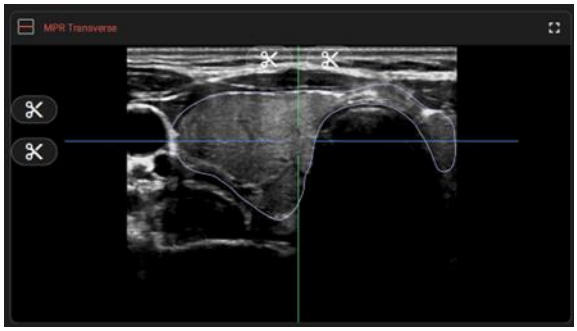

The side is automatically detected. By clicking "Right" or "Left" the side can also be selected by the user according to the analysed scan.


The automatic Lobe Volume is displayed.
There are now the options of "correction tool", "cut tool", "manual measurement tool"

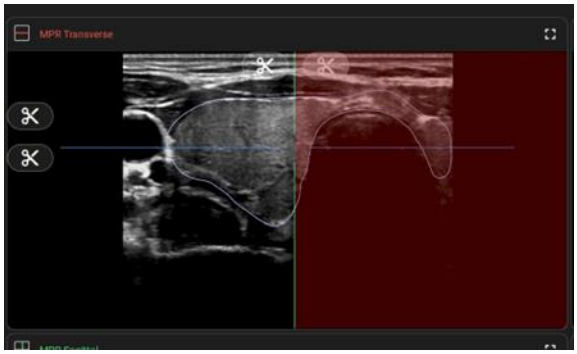


Manual lobe segmentation correction tool.
Here the user can adapt the automatic segmentation manually, by clicking the left and right button as marked in the image.
"-" click and hold this button while moving over the parts of the segmentation which should be excluded from the volume segmentation.
"+" click and hold this button while moving over the parts of the segmentation which should be included into the volume segmentation

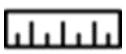
Press the scissor icon, to cut parts of the lobe volume.




Cutting icons are displayed along the planes.

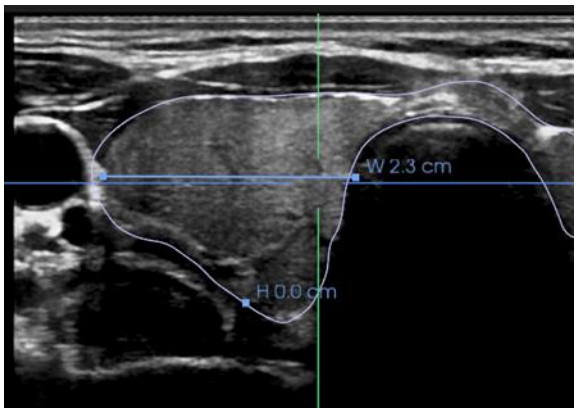



Hover with the mouse over the icon gives a preview of the to cut area.

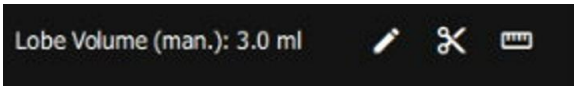


3-line manual measurement tool

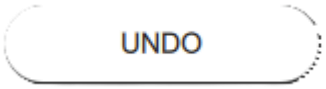
(**W**idth, **H**eight and **L**ength).




Place the start and end point of each line by clicking in the 2D view.
During the measurement, the respective letter is displayed next to the cursor.



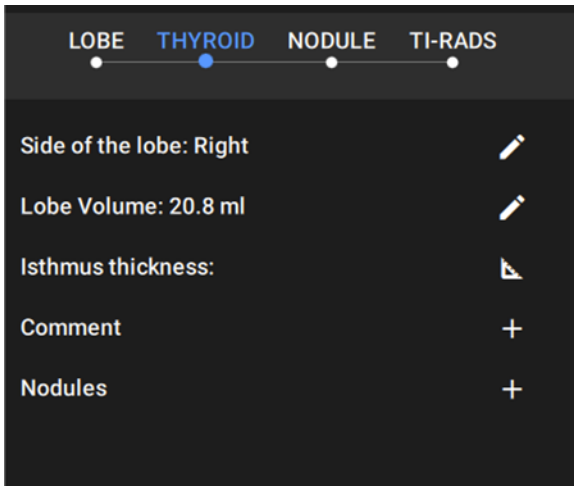

Lobe volume is adapted to the new cut volume.




Jumps one step back, which was performed in the respective tool.


Resets all steps, which were performed in the respective tool.


Accepts and saves the lobe including all editing steps to proceed with the analysis.




The summary of the lobe analysis is displayed including the side and volume of the lobe.

Side/ lobe volume can be edited. Jumps back to the respective menu.

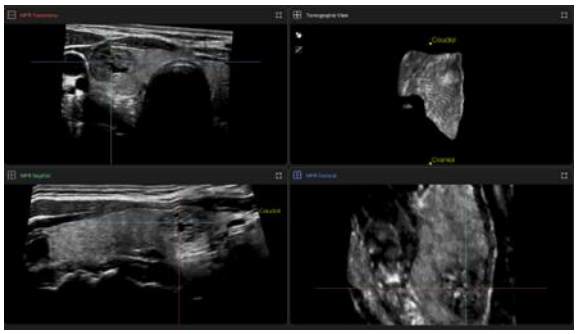
Create a 2-point line measurement in the MPR to measure the Isthmus thickness.



Create a comment by clicking on the plus symbol. Text box opens to add text. Save the comment or discard to return to the previous menu.


Icon of the comment appears after the comment is added


Add a nodule to the analysis by clicking on the plus.

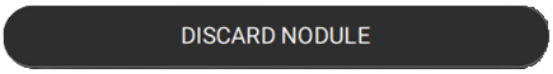


Move the MPRs to the centre of the targeted nodule.
Click in the middle. The detected nodule is shown in the MPR and 3D view.
This leads automatically to the manual nodule segmentation correction tool.

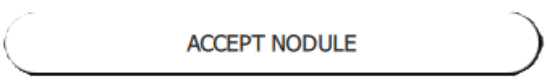
Here the user can adapt the automatic segmentation manually, by clicking the left and right button as marked in the image.

"-" click and hold this button while moving over the parts of the segmentation which should be excluded from the volume segmentation.

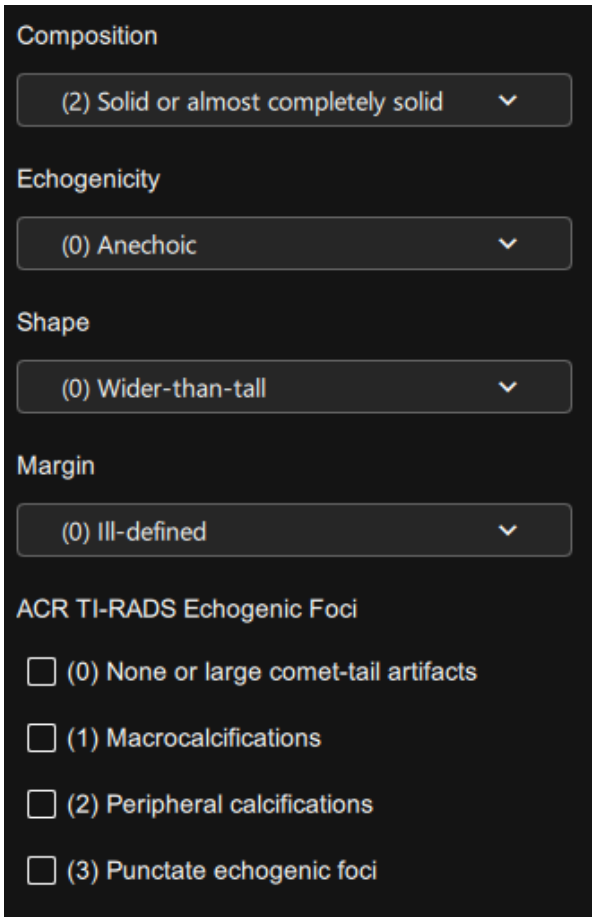
"+" click and hold this button while moving over the parts of the segmentation which should be included into the volume segmentation




Discards the segmentation of the selected nodule including all edits.




Accepts the segmentation of the nodule including all edits. Leads to the next step in the analysis.




The software predicts:

**Composition**

---

(0) Cystic or almost completely cystic
(0) Spongiform
(1) Mixed cystic and solid
(2) Solid or almost completely solid

**Echogenicity**

---

(0) Anechoic
(1) Hyperechoic or isoechoic c
(2) Hypoechoic
(3) Very hypoechoic

**Shape**

---

(0) Wider-than-tall
(3) Taller-than-wide

**Margin**

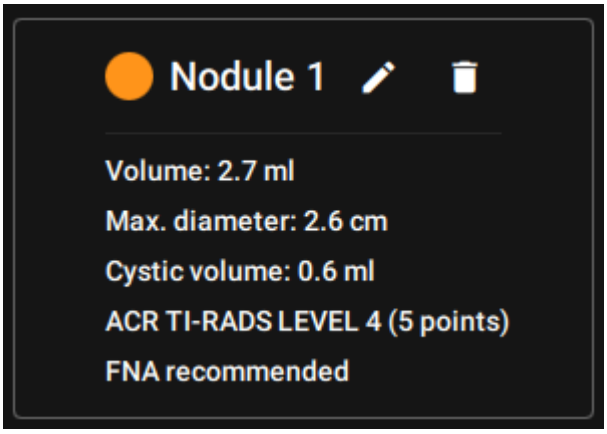
---

(0) Ill-defined
(0) Smooth
(2) Lobulated or irregular
(3) Extra-thyroidal extension

**ACR TI-RADS Echogenic Foci**

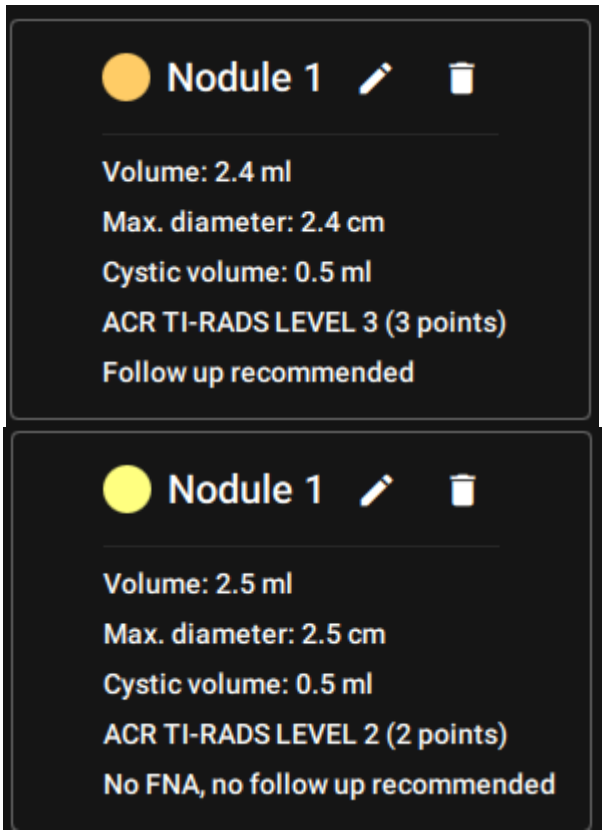
(0) None or large comet-tail artifacts
(1) Macrocalcifications
(2) Peripheral calcifications
(3) Punctuate echogenic foci

After reviewing and maybe adjusting, accept the selection.

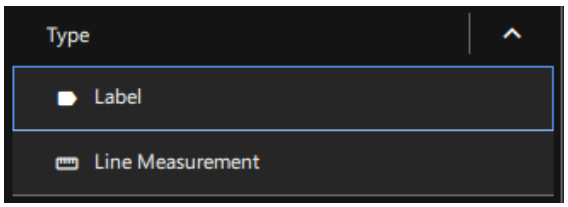



Overview of the nodule.
Delete or edit the shown nodule.
The arrow let you jump between multiple nodules.
Three recommendations for Nodule are available:

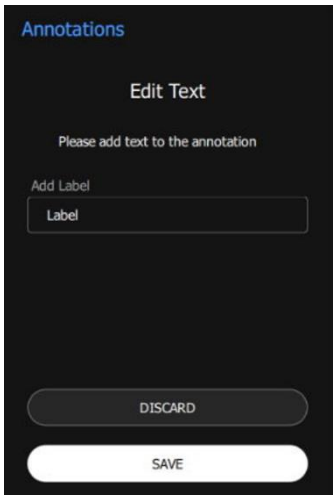
1. FNA recommended
2. Follow up recommended
3. No FNA, no follow up recommended


Nodule 1
Volume: 2.4 ml
Max. diameter: 2.4 cm
Cystic volume: 0.5 ml
ACR TI-RADS LEVEL 3 (3 points)
Follow up recommended
Nodule 1
Volume: 2.5 ml
Max. diameter: 2.5 cm
Cystic volume: 0.5 ml
ACR TI-RADS LEVEL 2 (2 points)
No FNA, no follow up recommended

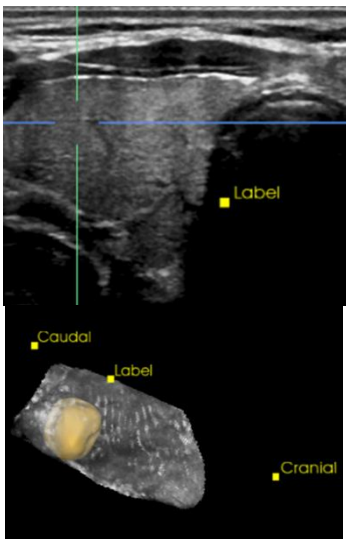
## 6.10 Annotations



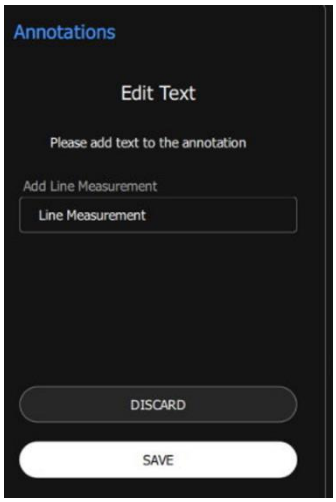

Choose between Label and Line Measurements.



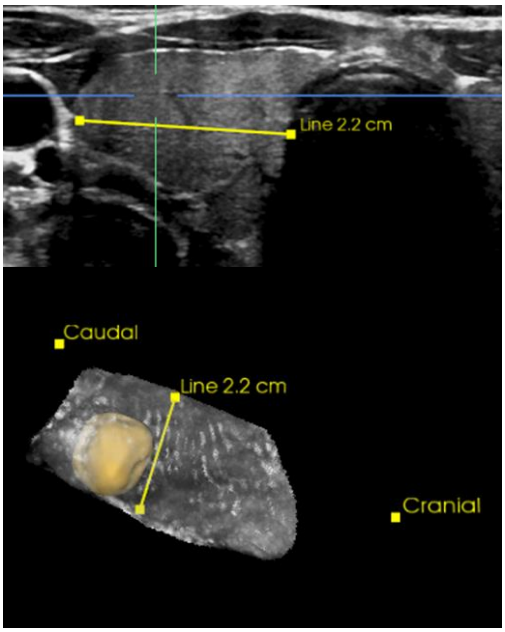

Target the marker in the MPR planes.
Change Label name, discard or save.



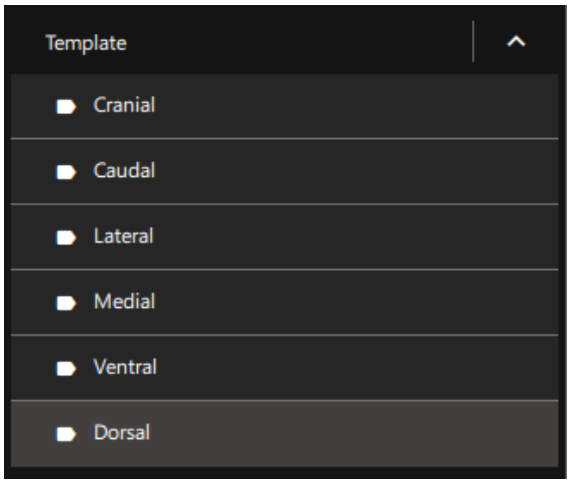

Appearance of the Label in the MPRs and the 3D volume



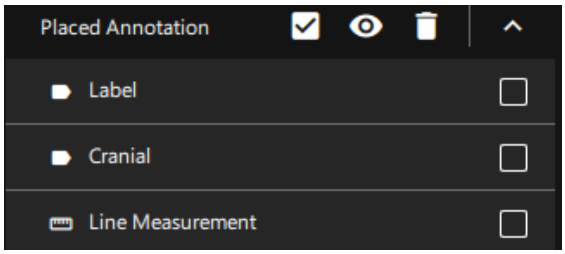

Target the first measurement pint in the MPR plane. Click the second point to finish the measurement. The measured value is displayed next to the measurement line.




Appearance of Line Measurement in the MPRs and the 3D volume




Select a predefined Label and place it in the MPR plane.




Placed annotations are listed.
Select each annotation by the checkbox.

Select / unselect all checkboxes.

Disable / Enable selected annotations.

Delete selected annotations.

# 7 Taking out of Operation

## 7.1 Switching Off and Storing the Device

The application is shut down by the Ultrasound environment.

Ensure you saved all relevant information.

## 7.2 Charging and Storing the Device

Charging of PIUR Sensor is done wirelessly.

1. Place PIUR Sensor on a charging pad.
2. A charging label printed on the bottom of PIUR Sensor must align with the center of the charging pad.

*Figure 4: PIUR Sensor on a charging pad*

LED feedback:

| **Illumination** | **Information about system status** |
|---|---|
| ▪ Blinking green | On the charging pad, battery is charging |
| ▪ Static green | On the charging pad, battery is fully charged |
| ▪ Static blue | Off the charger, Sensor is connected and charged |
| ▪ Blinking blue | Off the charger, Sensor is not connected and charged |
| ▪ Static yellow | Off the charger, Sensor is connected and less than 15% charged |
| ▪ Blinking yellow | Off the charger, Sensor is not connected and less than 15% charged |

## 7.3 Disinfecting and Cleaning

### 7.3.1 Cleaning and Disinfecting the PIUR Sensor

The PIUR Sensor must be cleaned before and after each use in accordance with the applicable disinfection and cleaning rules.

1. Remove the sensor housing from the attachment plate by levering it diagonally downwards with one hand.

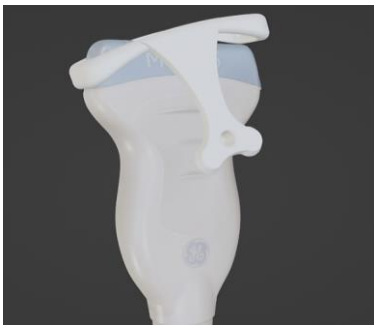
2. Carefully remove all soiling and residues from the sensor housing, using a soft damp cloth if necessary.
3. Wipe the sensor surface with CaviWipesTM.
4. Let the sensor dry for about 2 minutes.

Safety Notice
Never submerge the PIUR sensor in disinfectant or any other liquid. Submerging of the component results in a loss of warranty and may cause damage to the system and endanger the patient. If these components are accidentally submerged into any substance, please contact the manufacturer.

### 7.3.2 Removing and Cleaning the Bracket

Clean and disinfect the attachment after every patient examination, as follows:

1. Release the attachment from the anchoring by applying slight pressure to the attachment plate and remove it from the ultrasound probe.



2. Wipe attachment, with CaviWipesTM.
3. Let the attachment dry for about 2 minutes.

Safety Notice
Never sterilize (e.g. autoclave) the components of the system. Sterilization of any of these components results in a loss of warranty and can cause damage to the system and endanger the patient. If these components are accidentally sterilized, please contact the manufacturer.

**Before starting cleaning and disinfection, please note the following:**

- None of the (electrical) components shall have any visible damage; otherwise, water or cleaning/disinfection solution could penetrate. This could cause malfunctions or damage to the electrical components.
- Do not apply diving cleaning or disinfection.

Strictly follow the application instructions specified on the detergent used, disinfectant!

In accordance with the statutory hygiene regulations for the prevention of infections and the requirements for the treatment of medical devices, a careful and effective cleaning and disinfection must be carried out after each use.

If coarse impurities are visible, they must be removed with an appropriate cleaner (or disinfectant cleaner) before disinfection.

Appropriate means of disinfection must be used, the material compatibility of which has been demonstrated:

| | |
|---|---|
| **Active ingredient** | Quaternary ammonium germicidal detergent solution |
| **Cleaning Agents** | CaviWipes™ (Disinfectant Wipes) |
| **Dry time** | 2 Minutes |

**WARNING:** Do not use any liquid or aerosol cleaner, only determined cleaning solution (agent) specified above.

## 7.4 Disposing of PIUR tUS inside software

To uninstall the PIUR tUS inside software from the device please contact Service. Contact data can be found in section 6.

## 7.5 Disposing of PIUR Sensor

The PIUR Sensor must be disposed in accordance with the national guidelines for electronic scrap. Alternatively, the device can be sent back to the manufacturer for disposal.

# 8 Service and Maintenance

## 8.1 Contact

service@piurimaging.com

Hotline: +43-12 650 16 8

Please write down the software version before contacting our service team. You can find the software version number in the Info screen of PIUR tUS inside system on the information icon (see chapter 6.3).

## 8.2 Maintenance Interval

PIUR tUS inside does not require maintenance.

**Information:** Batteries Cycle Life at room temperature may drop to 80% of minimum capacity after 500 cycles or 2 years (depending on charging).

PIUR Sensor will anyway indicate when batteries are depleted. RM-132

## 8.3 Software Update

The user is not permitted to carry out software updates. Software updates are performed by trained service personnel or provided through the GE Healthcare app store.

## 8.4 Procedure in Case of Faults and Defects

**Safety Notice:** If malfunctions and defects occur.
**Occurrence of malfunctions and defects can lead to personal injury or damage to the device.**

- If malfunctions and defects occur, discontinue the use of the PIUR tUS inside system and inform our service team via the above contact details.

# 9 Technical Data

## 9.1 Compatibility

Supported ultrasound device:

| | |
|---|---|
| Device name: | GE Healthcare LOGIQ E10 |
| Version compatibility: | R4.1 |

| | |
|---|---|
| Device name: | GE Healthcare LOGIQ E10s |
| Version compatibility: | R4.1 |

| | |
|---|---|
| Device name: | GE Healthcare LOGIQ Fortis |
| Version compatibility: | R4.1 |

Any other compatible device has to fulfil at least the minimum hardware requirements for PIUR tUS inside:

| | |
|---|---|
| Operating system: | Windows 10 IoT Enterprise |
| Display: | Full- HD Display 1920x1080 Pixel |
| Graphic Card: | NVIDIA Graphics Card with CUDA |
| Processor: | Dual-Core Processor i.e. Intel i5 or similar from AMD |
| RAM: | 6GB RAM (8GB installed, 2GB reserved for beamforming) |
| Operating system: | Windows 10 IoT Enterprise LTSC 2019 (64bit) - version 1809 |
| Display: | Full- HD Display 1920x1080 Pixel (app res: 1552x970) |
| Graphic Card: | NVIDIA Graphics Card with CUDA |
| Processor: | Dual-Core Processor z.B. Intel i5 or similar from AMD |
| RAM: | 6GB RAM (8GB installed, 2GB reserved for beamforming) |
| Wireless connection: | Bluetooth 4.0 or higher |

## 9.2 Technical Data

| | PIUR Sensor |
|---|---|
| **Voltage** | 3,7 VDC (Lithium Polymer) |
| **Power input** | ~ 0,15W |
| **Dimensions** | 41,8x56,2x25,3 mm |
| **Mass (without packaging)** | 40 g |
| **Lifetime** | 2 years RM-132 |
| **Storage and transport condition** | Temperature: -10 °C to +60 °C<br>Relative humidity: 10 % – 90 % (no outside storage)<br>atmospheric pressure: 50 kPa to 106 kPa EN 60601-1-2:2015 Anhang A zu 7.9.3.1 RM-131 |
| **Recommended operating conditions** | Temperature: +10 °C to +30 °C<br>Relative Humidity: 30 % to 75 % EN 60601-1-2:2015 Anhang A zu 7.9.3.1<br>atmospheric pressure: 70kPa to 106 kPa EN 60601-1-2:2015 Anhang A zu 7.9.3.1 |
| **Recommended operating altitude** | Maximal 2000 m |

## 9.3 Measurement Function

**Safety Notice:** Accurate measurements can only be performed in the "Performance"-Domain of Tracking Sensor  same room

In case of leaving the "Performance"-Domain during a measurement a warning will appear.

The system accuracy is determined by a percental measurement error computed relative to the ground truth. The protocol measures volume of known dimensions and the systems calculated value is compared to the known ground truth. The details can be found in the accuracy validation study performed.

- **Volumetric accuracy G2 sensor:** considered as volume measurement using all three dimensions of the dataset

  Relative measurement error: Mean 9.49 %, Median 17.12%

- **Volumetric accuracy G3 sensor:** considered as volume measurement using all three dimensions of the dataset

  Relative measurement error: Mean 4.73%, Median 6.79%

## 9.4 Classification

| | PIUR Sensor |
|---|---|
| Protection class | Internally powered device |
| IP classification | IPx5 |

## 9.5 Electromagnetic compatibility (EMC)

The PIUR Sensor fulfils the requirements of the standards:EN 60601-1-2:2015,

- EN 60601-1-2:2015 + A1:2021
- EN 60601-2-37:2016
- EN 301 489-1 V2.2.3 (2019-11)
- DRAFT EN 301 489-17 V3.2.5 (2022-08)

The PIUR Sensor is classified according to CISPR 11 as group 1, class B.

Under EN 60601-1-2, the DUT is classified into group 1, class B, according to CISPR 11 and into class B according to CISPR 32.

Under ETSI EN 301 489-1, the DUT is classified into class B according to CISPR 32.

| | PIUR Sensor |
|---|---|
| Frequency band of reception | 2,4 GHz ISM frequency band EN 60601-1-2:2015 5.2.2.3 |
| Bandwidth of the receiving section | max. 1 Mbit/s |
| Frequency band of transmission | 2,4 GHz ISM frequency band EN 60601-1-2:2015 5.2.2.4 |
| Type and frequency characteristics of the modulation | IEEE 802.15.1 EN 60601-1-2:2015 5.2.2.4 |
| Effective radiated power | 5 dBm EN 60601-1-2:2015 5.2.2.4 |